

Melonee Wise

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EDUCATION

M.S. Mechanical Engineering <i>University of Illinois Urbana Champaign</i>	2004 – 2005 Urbana Champaign
B.S. Physics Engineering <i>University of Illinois Urbana Champaign</i>	2000 – 2004 Urbana Champaign
B.S. Mechanical Engineering <i>University of Illinois Urbana Champaign</i>	2000 – 2004 Urbana Champaign

PROFESSIONAL EXPERIENCE

VP/GM Robotics Automation <i>Zebra Technologies</i> Act as the CTO of the Robotics Automation business unit created around the Fetch Robotics acquisition.	08-2021 – present San Jose, United States
CEO and Co-founder <i>Fetch Robotics</i> Led and built the Fetch business until its acquisition by Zebra Technologies for \$305M in August 2021	08-2014 – 08-2021 San Jose, United States
CEO and Co-founder <i>Unbounded Robotics</i> Developed a next generation low cost mobile manipulation robot for the research market.	01-2013 – 06-2014 San Jose, United States
Robot Development Manager <i>Willow Garage</i> Led a team of engineers and designers to develop next generation mobile manipulation hardware.	01-2007 – 01-2013 Menlo Park, United States

SKILLS

CAD <i>Solidworks, Autodesk, Pro Engineer, etc</i>	● ● ● ● ●	Robotics <i>Navigation, Manipulation, ROS, etc</i>	● ● ● ● ●
Programming Languages <i>C++, Python</i>	● ● ● ● ●	Prototyping <i>3D printing, laser cutting, etc</i>	● ● ● ● ●

AWARDS

Engelberger Award for Technology - The "Nobel Prize" of Robotics <i>Advancing Automation Association (A3)</i>	2022
MechSE Award for Distinguished Service <i>Department of Mechanical Engineering at University of Illinois at Urbana Champaign</i>	2022
Supply Chain Woman of the Year 🔗 <i>Demand Chain Executive</i>	2021
Technology Pioneer 🔗 <i>World Economic Forum</i>	2018
MechSE Distinguished Alumni Award <i>Department of Mechanical Engineering at University of Illinois at Urbana Champaign</i>	2016
MIT TR35 - Top Innovators Under 35 🔗 <i>MIT Technology Review</i>	2015

PUBLICATIONS

Fetch & Freight: Standard Platforms for Service Robot Applications <i>International Joint Conference on Artificial Intelligence</i>	07-2016
Towards Autonomous Robotic Butlers: Lessons Learned with the PR2 <i>International Conference on Robotics and Automation</i>	05-2011
Autonomous Door Opening and Plugging In with a Personal Robot <i>International Conference on Robotics and Automation</i>	05-2010
Model-based, hierarchical control of a mobile manipulation platform <i>ICAPS Workshop on Planning and Plan Execution for Real-World Systems</i>	09-2009
Application and analysis of a robust trajectory tracking controller for under-characterized autonomous vehicles <i>Conference on Control Applications</i>	09-2008

PATENTS

System and method for order fulfillment using robots <i>US 11,137,742</i>	2021
System and method for computing a probability that an object comprises a target using segment points <i>US 11,087,239</i>	2021
Method and system for facility monitoring and reporting to improve safety using robots <i>US 11,059,177</i>	2021
Method and system for facility monitoring and reporting to improve safety using robots <i>US 11,059,176</i>	2021
Robotic cart configured for effective navigation and multi-orientation docking <i>US 10,908,601</i>	2021
Method and system for selecting a preferred robotic grasp of an object-of-interest using pairwise ranking <i>US 10,899,011</i>	2021
System and method for automatically annotating a map <i>US 10,853,561</i>	2020
System and method for computing a probability that an object comprises a target <i>US 10,699,219</i>	2020
System and method using robots to assist humans in order fulfillment <i>US 10,691,109</i>	2020
System and method using robots to assist humans in order fulfillment <i>S 10,562,707</i>	2020
System and method for computing a probability that an object comprises a target <i>US 10,515,319</i>	2019
System and method for order fulfillment using robots <i>US 10,423,150</i>	2019
System and method for load balancing of robots to create more equivalent task loads across task servers <i>US 10,363,659</i>	2019
System and method for responding to emergencies using robotic assistance <i>US 10,356,590</i>	2019
System and method for determining and promoting safety of a robotic payload <i>US 9,943,963</i>	2018
System and method for localization of robots <i>US 9,927,814</i>	2018

Robotic torso sensing system and method

US 9,827,669

2017

Steering column lock assembly and method of operating the same

US 7,406,845

2008